

This page shows how polarized light is reflected and transmitted by a level air-water surface. The geometry is the same as for the Level 1 discussion of Fresnel reflectance and transmittance of unpolarized light by a level sea surface. Now, however, the state of polarization of the incident light is described by a four-component Stokes vector, as described on the page on Stokes Vectors. Consequently, reflection and transmission by the surface are described by 4×4 matrices.

The state of polarization of a light field is specified by the four-component Stokes vector, whose elements are related to the complex amplitudes of the electric field vector \mathbf{E} resolved into directions that are parallel (E_{\parallel}) and perpendicular (E_{\perp}) to a conveniently chosen reference plane. However, there are two versions of the Stokes vector seen in the literature, and these two versions have different units and refer to different physical quantities. The *coherent Stokes vector* describes a quasi-monochromatic plane wave propagating in one exact direction, and the vector components have units of power per unit area (i.e., irradiance) on a small surface element perpendicular to the direction of propagation. The *diffuse Stokes vector* describes light propagating in a small set of directions surrounding a particular direction and has units of power per unit area per unit solid angle (i.e., radiance). It is the diffuse Stokes vector that appears in the vector radiative transfer equation. The differences in coherent and diffuse Stokes vectors are rigorously discussed in (Mischenko, 2008).

For either air- or water-incident light, \underline{S}_i denotes the diffuse Stokes vector of the incident light, \underline{S}_r is the reflected light, and \underline{S}_t is the transmitted light. Angles θ_i , θ_r , and θ_t are the incident, reflected, and transmitted directions of the light propagation measured relative to the normal to the surface. For a level surface, \underline{S}_i , \underline{S}_r , and \underline{S}_t all lie in the same plane.

There are four matrices to describe reflection and transmission: \underline{R}_{aw} describes how air-incident light is reflected by the water surface back to the air, \underline{T}_{aw} describes how air-incident light is transmitted through the surface into the water, \underline{R}_{wa} reflects water-incident light back to the water, and \underline{T}_{wa} transmits light from the water into the air. However, because \underline{S}_i , \underline{S}_r , and \underline{S}_t are coplanar, scattering by the level surface does not involve rotation matrices as does scattering within the water body. (Or, from another viewpoint, the incident and final meridian planes and the scattering plane are all the same, the rotation angles between meridian and scattering planes are 0, and the rotation matrices reduce to identity matrices.)

The reflection and (especially) transmission of polarized light by a dielectric surface such as a level water surface are rather complicated processes, and the literature contains a number of different (and, indeed, sometimes incorrect) mathematical formulations of the equations. The formulas given in (Garcia, 2012) are used here. Note, however, that although the equations in (Garcia, 2012) are correct, some of his derivations and interpretations are incorrect, as explained by (Zhai, et al. (2012)). Both papers must be used to understand the equations now presented. The equations in Garcia will be referenced by (G21) and so on; the corresponding equations in (Zhai et al. (2012)) will be referenced as (Z5), etc.

The reflectance and transmittance matrices have a general formulation for the interface between any two dielectric media a and b . Let n_a be the index of refraction of medium a and n_b be that of medium b . In general n_a and n_b are complex numbers, but for the air-water surface we take $n_{air} = 1$ and $n_{water} \approx 1.34$ to be real indices of refraction. For reflection, the reflected angle θ_r equals the incident angle θ_i . For transmission from a to b , the transmitted angle is given by Snel's law, $n_a \sin \theta_a = n_b \sin \theta_b$, or

$$\theta_b = \arcsin\left(\frac{n_a \sin \theta_i}{n_b}\right). \quad (1)$$

For water-incident light, $n_a = n_{water}$ and $n_b = n_{air}$, in which case the transmitted angle becomes undefined beyond the *critical angle for total internal reflection*, which for water is $\theta_c = \arcsin(1/n_{water}) \approx 48$ deg. For water-incident angles greater than θ_c the incident light is totally reflected back to the water and no light is transmitted to the air.

Let \underline{R}_{ab} denote the reflectance matrix for light incident from medium a and reflected back by medium b . \underline{R}_{ab} thus represents either \underline{R}_{aw} or \underline{R}_{wa} . Likewise, let \underline{T}_{ab} denote the reflectance matrix for light incident from medium a and transmitted through the surface into medium b . \underline{T}_{ab} thus represents either \underline{T}_{aw} or \underline{T}_{wa} .

With these preliminaries, the reflectance matrix \underline{R}_{ab} is (G10)

$$\underline{R}_{ab} = \begin{bmatrix} \frac{1}{2}(R_{\parallel}R_{\parallel}^* + R_{\perp}R_{\perp}^*) & \frac{1}{2}(R_{\parallel}R_{\parallel}^* - R_{\perp}R_{\perp}^*) & 0 & 0 \\ \frac{1}{2}(R_{\parallel}R_{\parallel}^* - R_{\perp}R_{\perp}^*) & \frac{1}{2}(R_{\parallel}R_{\parallel}^* + R_{\perp}R_{\perp}^*) & 0 & 0 \\ 0 & 0 & \Re\{R_{\parallel}R_{\perp}^*\} & \Im\{R_{\parallel}R_{\perp}^*\} \\ 0 & 0 & -\Im\{R_{\parallel}R_{\perp}^*\} & \Re\{R_{\parallel}R_{\perp}^*\} \end{bmatrix}. \quad (2)$$

Here $\Re\{R_{\parallel}R_{\perp}^*\}$ denotes the real part of $R_{\parallel}R_{\perp}^*$ and $\Im\{R_{\parallel}R_{\perp}^*\}$ is the imaginary part.

The transmission matrix \underline{T}_{ab} is (G11 or Z3)

$$\underline{T}_{ab} = f_T \begin{bmatrix} \frac{1}{2}(T_{\parallel}T_{\parallel}^* + T_{\perp}T_{\perp}^*) & \frac{1}{2}(T_{\parallel}T_{\parallel}^* - T_{\perp}T_{\perp}^*) & 0 & 0 \\ \frac{1}{2}(T_{\parallel}T_{\parallel}^* - T_{\perp}T_{\perp}^*) & \frac{1}{2}(T_{\parallel}T_{\parallel}^* + T_{\perp}T_{\perp}^*) & 0 & 0 \\ 0 & 0 & \Re\{T_{\parallel}T_{\perp}^*\} & \Im\{T_{\parallel}T_{\perp}^*\} \\ 0 & 0 & -\Im\{T_{\parallel}T_{\perp}^*\} & \Re\{T_{\parallel}T_{\perp}^*\} \end{bmatrix}. \quad (3)$$

The components of these equations are given by (G7):

$$R_{\parallel} = \& \frac{n_b \cos \theta_a - n_a \cos \theta_b}{n_b \cos \theta_a + n_a \cos \theta_b} \quad (4)$$

$$R_{\perp} = \& \frac{n_a \cos \theta_a - n_b \cos \theta_b}{n_a \cos \theta_a + n_b \cos \theta_b} \quad (5)$$

$$T_{\parallel} = \& \frac{2n_a \cos \theta_a}{n_b \cos \theta_a + n_a \cos \theta_b} \quad (6)$$

$$T_{\perp} = \& \frac{2n_a \cos \theta_a}{n_a \cos \theta_a + n_b \cos \theta_b}. \quad (7)$$

The factor f_T is defined below in Eq. (23). In general, the indices of refraction are complex numbers and these equations must be used. However, for real indices of refraction, the matrix elements can be simplified at the expense of having a special case for water-incident angles greater than the critical angle.

Define

$$n_{ab} = \frac{n_a}{n_b} \quad \text{and} \quad n_{ba} = \frac{n_b}{n_a}. \quad (8)$$

Then for the case of air-incident light, i.e., $n_a \leq n_b$, or water-incident light with the incident angle less than the critical angle, i.e., $n_a > n_b$ and $\theta_a < \theta_c$, the equations yield the real forms (G14 and G15)

$$R_{\parallel}R_{\parallel}^* = \& \left(\frac{\cos \theta_a - n_{ab} \cos \theta_b}{\cos \theta_a + n_{ab} \cos \theta_b} \right)^2 \quad (9)$$

$$R_{\perp}R_{\perp}^* = \& \left(\frac{n_{ab} \cos \theta_a - \cos \theta_b}{n_{ab} \cos \theta_a + \cos \theta_b} \right)^2 \quad (10)$$

$$\Re\{R_{\parallel}R_{\perp}^*\} = \& \left(\frac{\cos \theta_a - n_{ab} \cos \theta_b}{\cos \theta_a + n_{ab} \cos \theta_b} \right) \left(\frac{n_{ab} \cos \theta_a - \cos \theta_b}{n_{ab} \cos \theta_a + \cos \theta_b} \right) \quad (11)$$

$$\Im\{R_{\parallel}R_{\perp}^*\} = \& 0 \quad (12)$$

$$T_{\parallel}T_{\parallel}^* = \& \left(\frac{2n_{ab} \cos \theta_a}{\cos \theta_a + n_{ab} \cos \theta_b} \right)^2 \quad (13)$$

$$T_{\perp}T_{\perp}^* = \& \left(\frac{2n_{ab} \cos \theta_a}{n_{ab} \cos \theta_a + \cos \theta_b} \right)^2 \quad (14)$$

$$\Re\{T_{\parallel}T_{\perp}^*\} = \& \frac{4n_{ab}^2 \cos^2 \theta_a}{(\cos \theta_a + n_{ab} \cos \theta_b)(n_{ab} \cos \theta_a + \cos \theta_b)} \quad (15)$$

$$\Im\{T_{\parallel}T_{\perp}^*\} = \& 0. \quad (16)$$

It should be noted that for the case of normal incidence, $\theta_i = 0$, both $R_{\parallel}R_{\parallel}^*$ and $R_{\perp}R_{\perp}^*$ reduce to

$$R_{\parallel}R_{\parallel}^* = R_{\perp}R_{\perp}^* = \left(\frac{n_b - n_a}{n_b + n_a} \right)^2. \quad (17)$$

This gives a reflectance of $R_{ab}(\theta_i = 0) = 0.021$ for $n_{water} = 1.34$, for both air- and water-incident light.

For the case of total internal reflection, i.e., $n_a > n_b$ and $\theta_a \geq \theta_c$, the following equations are to be used (G22):

$$R_{\parallel}R_{\parallel}^* = \& 1 \quad (18)$$

$$R_{\perp}R_{\perp}^* = \& 1 \quad (19)$$

$$\Re\{R_{\parallel}R_{\perp}^*\} = \& \frac{2 \sin^4 \theta_a}{1 - (1 + n_{ba}^2) \cos^2 \theta_a} - 1 \quad (20)$$

$$\Im\{R_{\parallel}R_{\perp}^*\} = \& - \frac{2 \cos \theta_a \sin^2 \theta_a \sqrt{\sin^2 \theta_a - n_{ba}^2}}{1 - (1 + n_{ba}^2) \cos^2 \theta_a} \quad (21)$$

and all elements of the transmission matrix elements are 0:

$$\underline{T}_{ab} = \underline{T}_{wa} = \underline{0}. \quad (22)$$

Finally, the all-important transmission factor f_T in Eq. (3) is given by

$$f_T = n_{ba}^3 \left(\frac{\cos \theta_b}{\cos \theta_a} \right) \quad (\text{for diffuse Stokes vectors}), \quad (23)$$

when computing the transmittance for diffuse Stokes vectors. These equations give everything needed to describe reflection and transmission of polarized light by a level sea surface.

Figure figure1 shows the \underline{R}_{aw} and \underline{T}_{aw} matrices as a function of incident angle θ_i for $n_{air} = 1$ and $n_{water} = 1.34$. The (1,1) matrix elements are shown in the upper-left plot, and the (4,4) elements are in the lower-right plot. The red curves are $\underline{R}_{aw}(\theta_i)$ and the blue curves are $\underline{T}_{aw}(\theta_i)$. The reflectance curve for $R_{aw}(1, 1)$ is the Fresnel reflectance for unpolarized light as given in the section on Fresnel formulas for unpolarized light: it starts at 0.021 for normal incidence and $n_{water} = 1.34$, and rises to 1 at grazing incidence. The transmission curve for $T_{aw}(1, 1)$ on the other hand may look incorrect because it has values greater than one. Its maximum value at normal incidence is

$$T_{aw}(1, 1) = \frac{4n_b^3}{(1 + n_b)^2} = 1.758 \quad (24)$$

However, this value is indeed correct and is a consequence of the fact that we are now dealing with a *diffuse* Stokes vector with units of radiance, and the n^2 law for radiance applies. The curves in Fig.(figure1) agree exactly with the corresponding plots in (Garcia, 2012) (his Figs. 1-3).

If we were dealing with *coherent* Stokes vectors with units of irradiance, then the f_T factor of Eq. (23) would be

$$f_T = n_{ba} \frac{\cos \theta_b}{\cos \theta_a} \quad (\text{for coherent Stokes vectors}). \quad (25)$$

The transmittance for normal incidence then would be $(4n_b)/(1 + n_b)^2 = 0.979$, which with the reflectance sums to one (and also sums to one for all other incident angles). As noted elsewhere, it is the Law of Conservation of Energy, not the law of conservation of radiance.

The vertical dotted line in Fig. (figure1) shows the location of Brewster's angle,

$$\theta_{Brew} = \arctan(n_b) \quad (26)$$

which is $\arctan(1.34) = 53.3$ deg in the present case. At this angle, $R_{aw}(1, 2) = R_{aw}(2, 1) = -R_{aw}(1, 1)$, and $R_{aw}(3, 3) = R_{aw}(4, 4) = 0$. In the present case $R_{aw}(1, 1) \approx 0.04$ at θ_{Brew} , and the reflection process $\underline{S}_r = \underline{R}_{aw}(\theta_i = \theta_{Brew})\underline{S}_i$ becomes

$$\underline{S}_r = \begin{bmatrix} 0.04 & -0.04 & 0 & 0 \\ -0.04 & 0.04 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} I \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0.04I \\ -0.04I \\ 0 \\ 0 \end{bmatrix}. \quad (27)$$

Thus, at Brewster's angle, unpolarized incident radiance is totally horizontally polarized upon reflection.

It should also be noted that the non-zero $T_{aw}(2, 1)$ means that unpolarized radiance becomes partly horizontally polarized upon transmission through the surface.

Figure (figure2) shows \underline{R}_{aw} and \underline{T}_{aw} as reduced scattering matrices, i.e. after dividing each element by its (1,1) component. These plots show more clearly the behavior of the \underline{R}_{aw} matrix elements at Brewster's angle. These curves agree exactly with the corresponding plots in (Kattawar and Adams (1989) (their Fig. 4).

Air-to-Water Reflection and Transmission Matrices

$n_a = 1.00, n_w = 1.34$

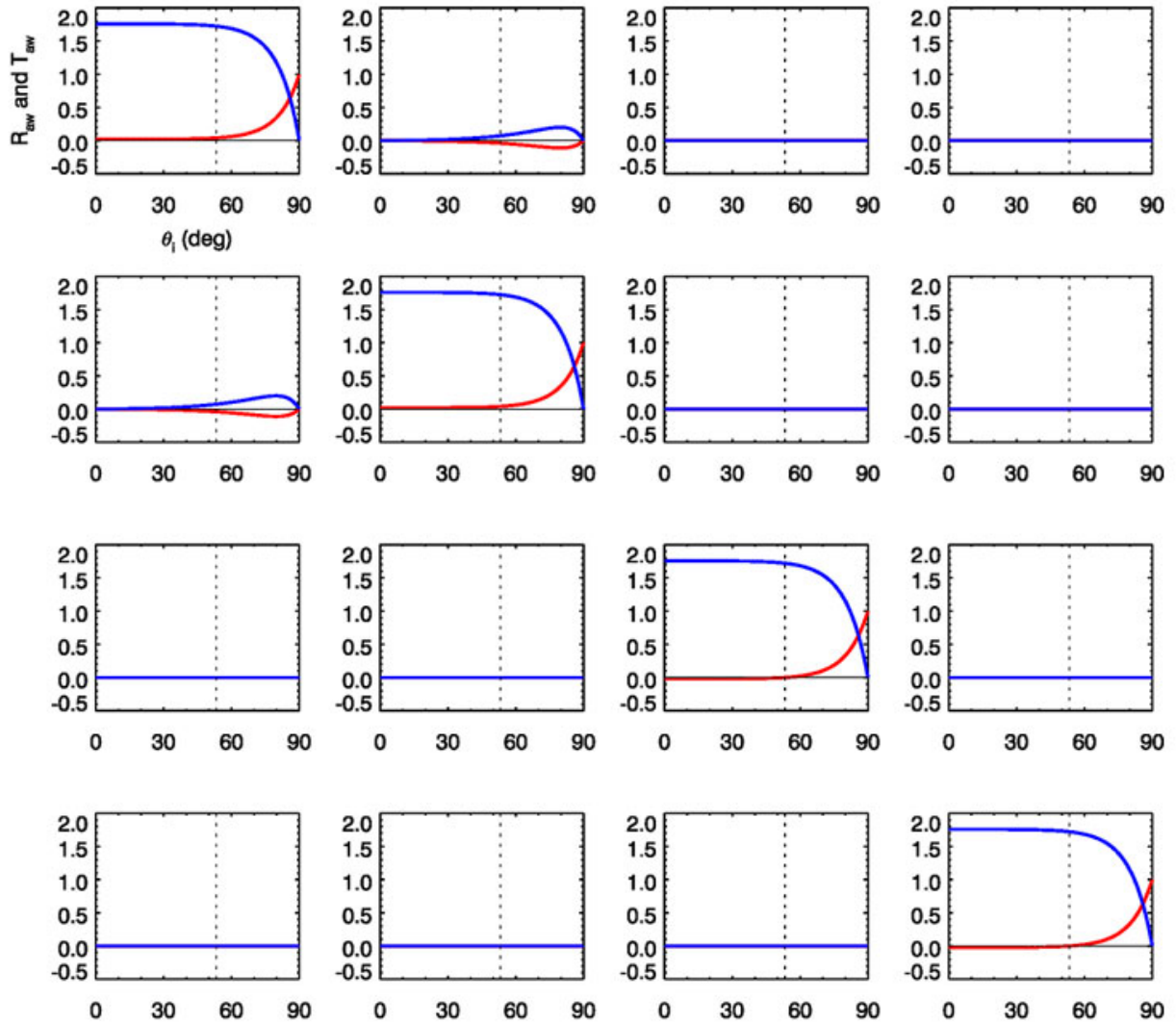


Figure 1: Reflectance and transmittance matrices as functions of the incident angle θ_i for air-incident radiance. \underline{R}_{aw} is in red and \underline{T}_{aw} is in blue. The vertical dotted line at $\theta_i = 53.3$ deg is Brewster's angle.

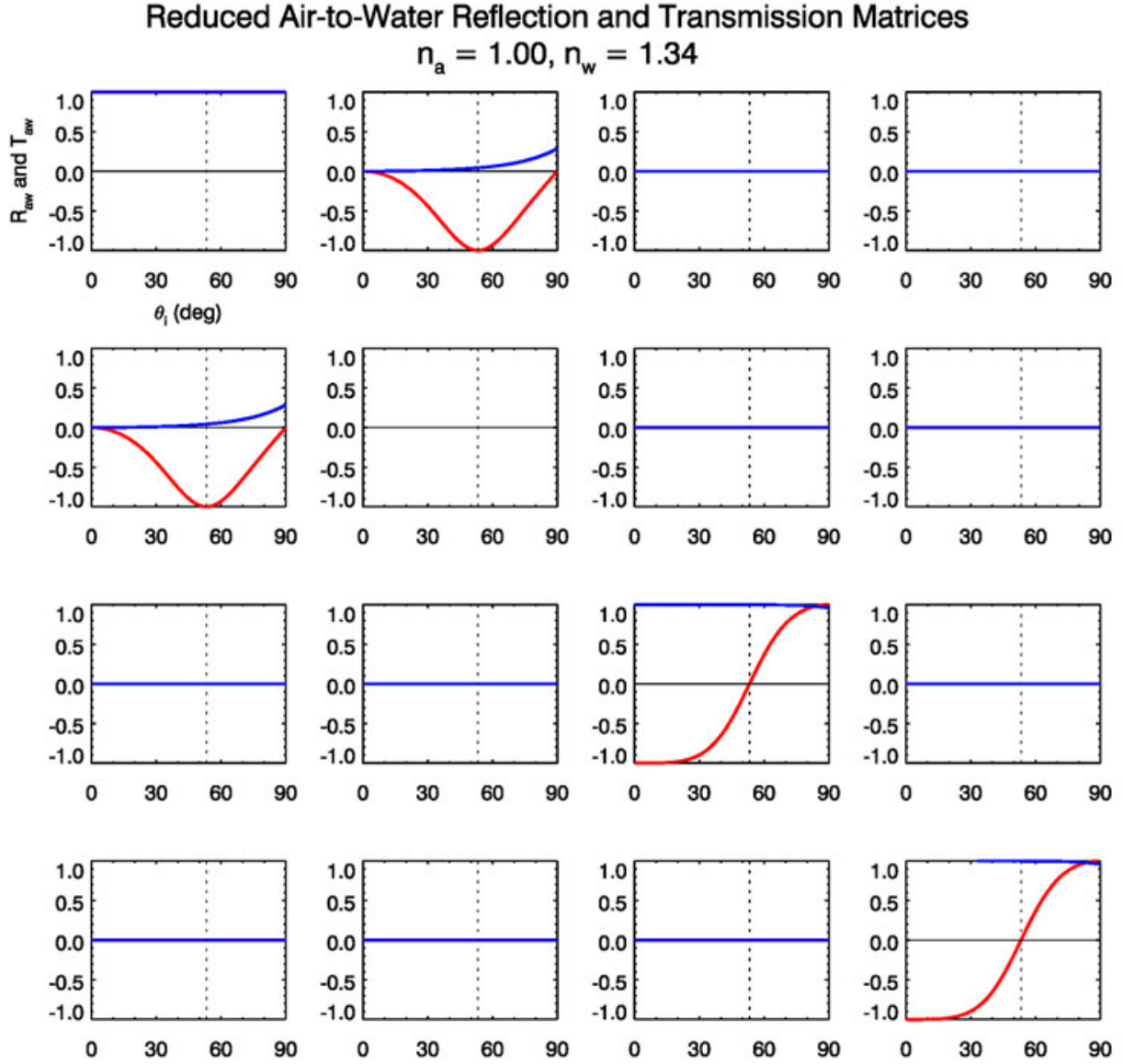


Figure 2: Reduced reflectance and transmittance matrices for air-incident radiance [the reflectance and transmittance matrices of Fig.(figure1) normalized by their (1,1) elements]. The vertical dotted line is Brewster's angle.

Figure (figure3) shows \underline{R}_{wa} and \underline{T}_{wa} . The vertical dotted line is at the critical angle for total internal reflection, which in the present case is $\theta_c = 48.3$ deg. For angles less than the critical angle, the transmission is never more than about 0.54. This again shows the n-squared law for radiance. In going from water to air, the in-water radiance is decreased by a factor of $1/n_{water}^2$ when crossing the surface because the solid angle in air is greater than that in water by a factor of n_{water}^2 . The (1,1) elements show that beyond the critical angle there is no transmission and total reflection. These curves agree with the corresponding plots in (Garcia (2012) (his Figs. 4-6).

Figure (figure4) shows the reduced water-to-air matrices. These curves agree with the corresponding plots in (Kattawar and Adams (1989) (their Fig. 5. The signs of the $\underline{T}_{wa}(3,4)$ and $\underline{T}_{wa}(4,3)$ elements are reversed in the original Fig. 5, which had a sign error.).

The non-zero matrix elements of course depend on incident angle as seen above, but also depend weakly on the wavelength via the wavelength dependence of n_{water} .

Water-to-Air Reflection and Transmission Matrices

$n_a = 1.00, n_w = 1.34$

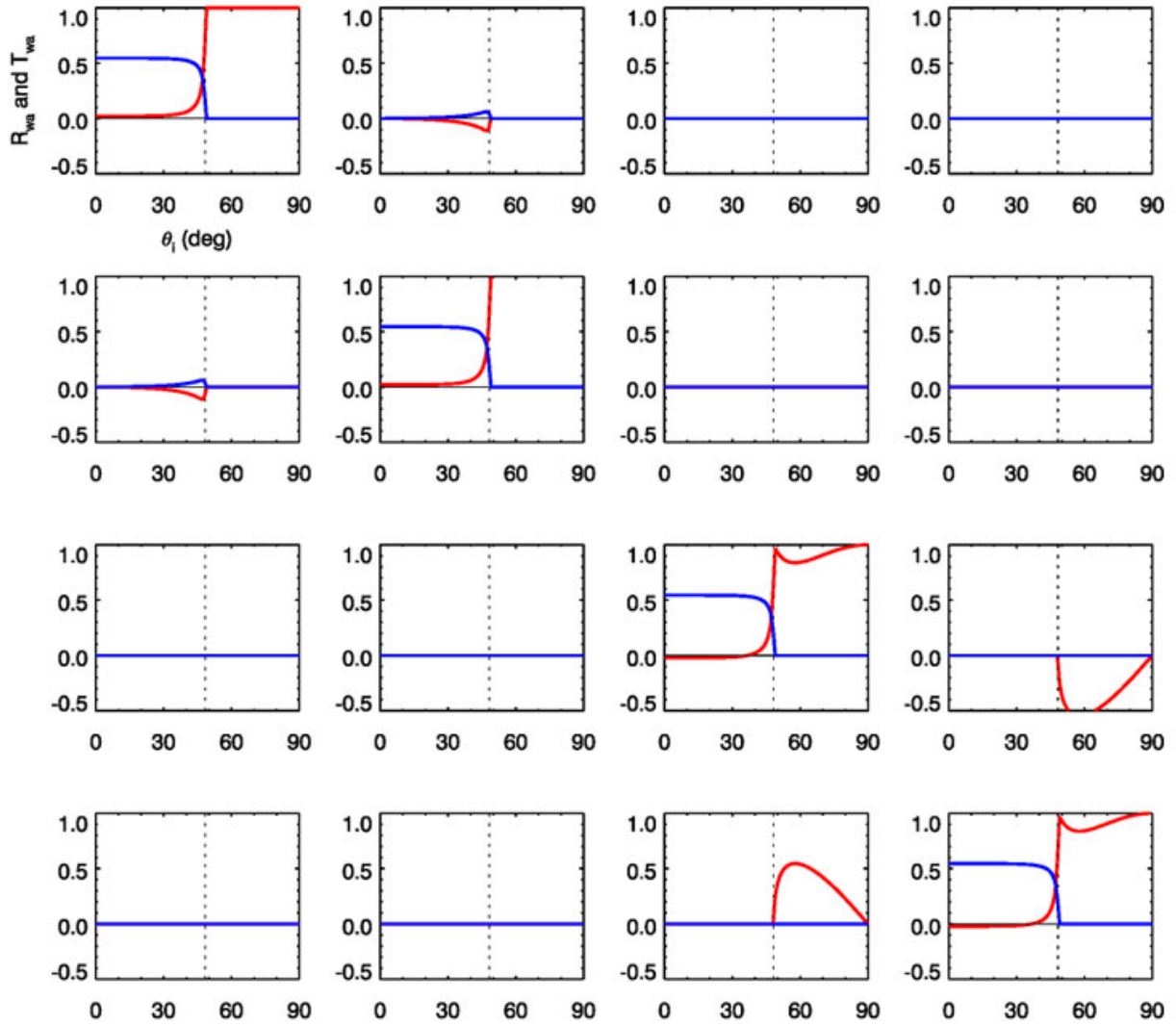


Figure 3: Reflectance and transmittance matrices as functions of the incident angle θ_i for water-incident radiance. R_{wa} is in red and T_{wa} is in blue. The vertical dotted line is the critical angle for total internal reflection.

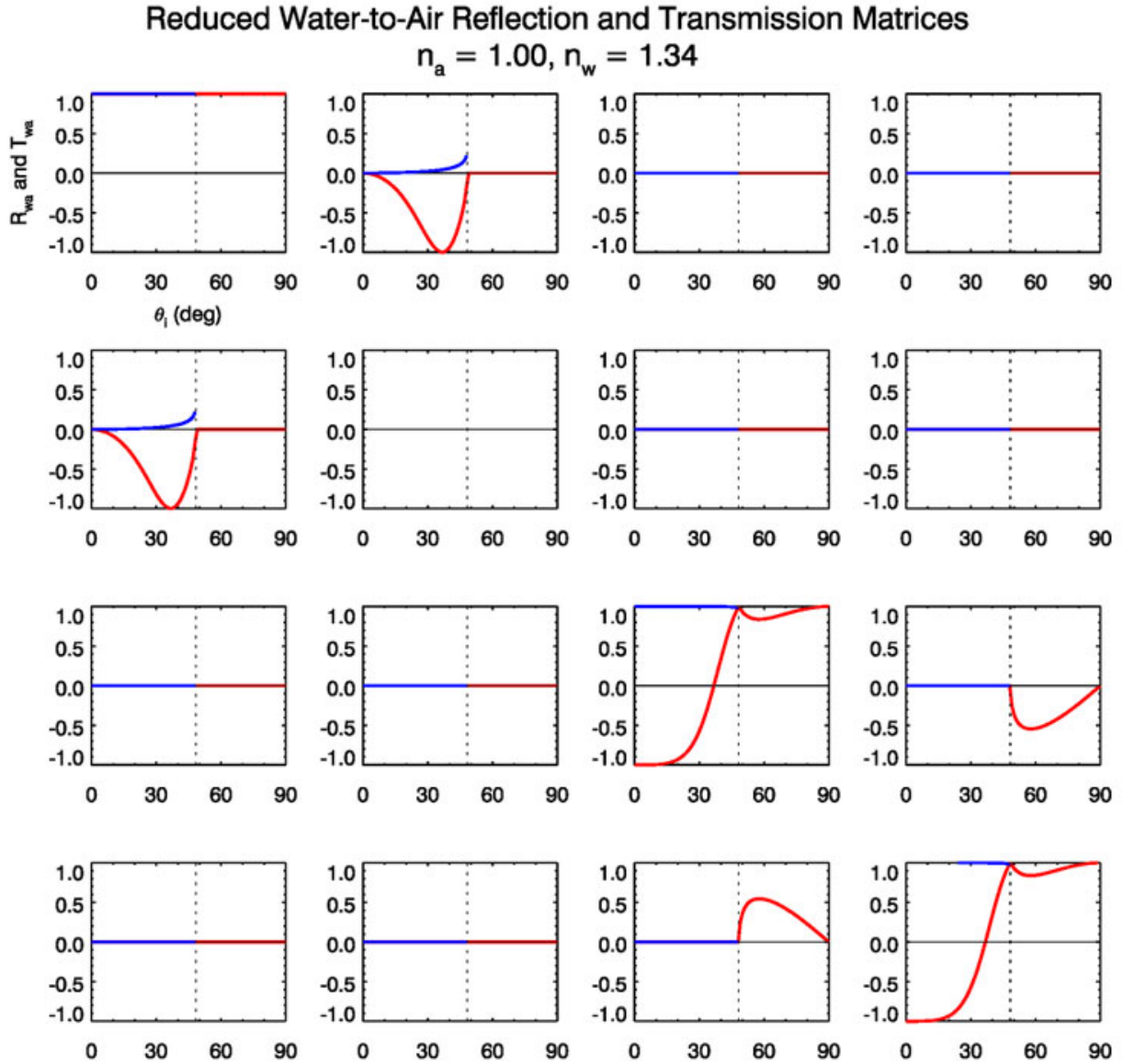


Figure 4: Reduced reflectance and transmittance matrices for air-incident radiance [the reflectance and transmittance matrices of Fig.(figure3) normalized by their (1,1) elements]. The 34 and 43 elements are the reverse of Fig. 5 in (Kattawar and Adams (1989) due to a sign error in the original paper.